

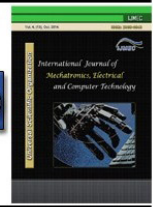


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Depth Control of the ROV with Fuzzy and Input Smoother PID Controller

Mohamad Hosein Salimi* and Seyed Moosa Ayati

Mechanical School, Tehran University

*Corresponding Author's E-mail: mhsalimi92@yahoo.com

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